

Taylor's University
School of Engineering
Scheme of Work

SOW/SoE/03/18

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|------------------------------|---|-----|----------------------------|-----------------------------|-----|-----|-----|-----|
| Module | Control Systems | | Module Code | EEE61203 | | | | |
| Module Status | Core | | Prerequisite | EEE60303 Signal and Systems | | | | |
| Semester/year | Semester 5,6 / Year 3 | | Date Prepared | 19 March 2018 | | | | |
| Lecturer | Dr. Phang Swee King B.Eng (Hons 1) Ph.D. | | Credit Hours | Three (3) | | | | |
| Period | Fourteen (14) weeks | | Date(s) of Revision | N/A | | | | |
| Module Synopsis | This subject deals with the open loop, closed loop control systems, mathematical models of different physical systems with concept of state space analysis. Time domain and frequency domain analysis are applied to determine the stability of systems. | | | | | | | |
| Contact hours | Lectures: 2 hours/week Tutorials: 1.5 hours/week (Average) Lab: 0.6 hours/week (Average) | | | | | | | |
| Evaluation | 25% Continuous Assessment 15% Test (Moderated) 60% Final Examination (Moderated) | | | | | | | |
| Learning Outcomes | On completion of this module, students will be able to: LO 1 Describe the time domain and frequency domain analysis of control systems. LO 2 Evaluate the concept of stability in control systems. LO 3 Solve electrical, mechanical and electromechanical systems. LO 4 Use block diagram reduction and signal flow graph methods to simplify complex systems. LO 5 Organise system equations into state-space format and derive the time-domain solution. LO 6 Design lead, lag and lead-lag compensated control systems. | | | | | | | |
| Assessment Methods | Distribution | (%) | LO1 | LO2 | LO3 | LO4 | LO5 | LO6 |
| | Final Examination | 60 | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | Test | 15 | ✓ | | ✓ | ✓ | | |
| | Laboratory Assessment | 25 | ✓ | ✓ | | | | |
| | Total | 100 | | | | | | |
| | Note: All internal assessments with feedback will be made available within 7 days after each assessment submission except Final Exam. | | | | | | | |
| Learning References | 1. Norman S. Nise. "Control Systems Engineering" Wiley, 6th Ed, 2011. 2. Katsuhiko Ogata. "Modern Control Engineering" Prentice-Hall, 2001. | | | | | | | |
| Additional References | 3. B.C. Kuo. "Automatic Control Systems" Prentice-Hall, 2002. 4. Richard C. Dorf. "Modern Control Systems" Prentice-Hall, 2000. | | | | | | | |

Program Outcomes (Electrical and Electronic Engineering)

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| PO1 | Apply the knowledge of mathematics, science, engineering practices, innovation techniques, entrepreneurship and human factors to provide value-adding solutions to complex Electrical and Electronic Engineering challenges. |
| PO2 | Identify, formulate, analyse and document complex engineering challenges to arrive at viable solutions and substantiated conclusions. |
| PO3 | Conceive, Design, Implement and Operate solutions for complex engineering challenges that meet specified requirements with appropriate consideration for public health and safety, cultural, societal, environmental and economical considerations. |
| PO4 | Conduct research and investigation into complex challenges using methods which include experiment design, analysis of data and synthesis of information to provide valid conclusions. |
| PO5 | Create, select and apply appropriate techniques, resources, and modern engineering and IT tools, including prediction and modelling, to complex engineering activities, with an awareness of the accompanying assumptions and limitations. |
| PO6 | Apply reasoning informed by contextual knowledge to assess societal, health, safety, legal, economical and cultural issues and the consequent responsibilities relevant to professional engineering practice. |
| PO7 | Explain the global impact of professional engineering solutions in societal, economical and environmental contexts and demonstrate knowledge of and need for sustainable development. |
| PO8 | Apply professional and ethical responsibilities of engineering practice. |
| PO9 | Effectively communicate complex engineering activities, both orally and in a written form, in both technical & non-technical contexts. |
| PO10 | Function effectively as an individual and in multidisciplinary settings with the capacity to be a leader. |
| PO11 | Recognise the importance of lifelong learning and engaging in continuous professional development activities in accordance with technological change. |
| PO12 | Effectively manage projects in multidisciplinary environments and apply project management tools and techniques to one's own work, as a member and leader in a team to satisfy stakeholders requirements. |

| Chapter | Topic | Week | Topic Outcomes (TO) | PO | LO | Delivery Methods |
|---|--|--------|--|-----|-----|------------------------|
| 1 | Introduction to control system terminology | Week 1 | Briefing on LO POs Examples of simple control systems, open loop and closed loop control systems, effect of feedback on overall gain, stability, sensitivity, external noise, types of feedback control systems, linear time invariant and time varying, nonlinear, discrete systems. | PO1 | LO1 | Lecture, Tutorial |
| 2 | Mathematical models of physical systems in frequency and time domain | Week 2 | Review of signal and systems, system model, system properties | PO1 | LO1 | Lecture, Tutorial |
| | | Week 3 | Laplace Transform review, formulation of differential equations for electrical, mechanical and electromechanical systems in frequency domain. | PO2 | LO3 | Lecture, Tutorial |
| 3 | Time domain analysis | Week 4 | Poles, zeros, and system response, impulse response, step response, first and second-order system specifications | PO2 | LO3 | Lecture, Tutorial |
| | | Week 5 | Steady state response, steady state error, stability, steady state performance, transient performance | PO2 | LO3 | Lecture, Tutorial |
| 4 | Reduction of multiple subsystems | Week 6 | Block diagrams, analysis of feedback systems, block diagram reduction, signal-flow graphs, single-flow graphs of state equations | PO1 | LO4 | Lecture, Tutorial |
| Lab 1: Application of MATLAB and Simulink in Analysis of Control System (Week 7) | | | | | | |
| Test (Week 7) | | | | | | |
| 5 | Stability | Week 8 | Open loop system, closed loop system, feedback control, Routh-Hurwitz criterion, stability in controlled system | PO2 | LO2 | Lecture, Tutorial |
| Lab 2: Design and Simulation of Feedback Control Systems (Week 9) | | | | | | |
| 6 | State-space analysis | Week 9 | Concepts of state, state variables, state vector, input vector, output vector, development of state models for simple systems *TES briefing (15 min) – week 9 | PO2 | LO5 | Lecture, Tutorial, Lab |

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|--|---------------------------------|---------|---|-----|-----|------------------------|
| 7 | Root locus analysis | Week 10 | The root locus concept, basic properties, magnitude and angle conditions, properties and construction of the complex root loci, root sensitivity, effects of adding poles and zeros. * Fill up TES student evaluation (15 min). Students are required to bring their own devices to complete the evaluation. – week 10 | PO2 | LO2 | Lecture, Tutorial |
| Lab 3: Root Locus Analysis on Systems (Week 11) | | | | | | |
| 8 | Frequency domain analysis | Week 11 | Frequency domain specification, correlation between time and frequency response, Bode plot, polar plot | PO1 | LO1 | Lecture, Tutorial, Lab |
| | | Week 12 | Nyquist plot, phase margin and gain margin, stability analysis * e-learning week | PO2 | LO2 | Lecture, Tutorial |
| Lab 4: Assessment on Control Systems Analysis (Week 13) | | | | | | |
| 9 | Design & compensation technique | Week 13 | Preliminary design considerations – lead, lag compensation techniques based on the frequency response approach | PO5 | LO6 | Lecture, Tutorial, Lab |
| | | Week 14 | Design lead - lag compensation techniques based on the frequency response approach. Review of coursework | PO5 | LO6 | Lecture, Tutorial |

Assessment Details:

| Assessment Details | | | |
|-----------------------------|------------|-----------------|------|
| Type | Details | Learning Domain | Mark |
| Final Examination | Individual | Cognitive | 60% |
| Test | Individual | Cognitive | 15% |
| Laboratory Assessment 1,2,3 | Group | Psychomotor | 15% |
| Laboratory Assessment 4 | Individual | Psychomotor | 10% |
| Total | | | 100% |













Assessment Schedule:

| Assessment Methods | | Week N ^o . | | | | | | | | | | | | | |
|--------------------|-----------------------|---------------------------|---|---|---|---|---|---|---|---|----|----|----|----|----|
| | | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 |
| Assessment Methods | Test | | | | | | | ✓ | | | | | | | |
| | Laboratory Assessment | | | | | | | ✓ | | ✓ | | ✓ | | ✓ | |
| | Final Examination | During Examination period | | | | | | | | | | | | | |

For all assessment, Turnitin similarity limit: 30%

Student is not allowed to transcribe directly (cut and paste) any material from another source into their submission.

PO-LO (TGC) mapping:

| | | Programme Outcomes (POs) and Taylor's Graduate Capabilities (TGC) | | | | | | | | | | | |
|------------------------|------|---|---|---|---|---|---|--|---|---|--|--|--|
| | | PO 1  | PO 2  | PO 3  | PO 4  | PO 5  | PO 6  | PO 7  | PO 8  | PO 9  | PO 10  | PO 11  | PO 12  |
| Learning Outcomes, LOs | LO 1 | ✓ | | | | | | | | | | | |
| | LO 2 | | ✓ | | | | | | | | | | |
| | LO 3 | | ✓ | | | | | | | | | | |
| | LO 4 | ✓ | | | | | | | | | | | |
| | LO 5 | | ✓ | | | | | | | | | | |
| | LO 6 | | | | | ✓ | | | | | | | |

Prepared By:

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 Dr. Chockalingam Aravind Vaithilingam
 Programme Director
 Date:

Remarks:

1. The Scheme of Work is to be distributed to the students in the first week of the semester.
2. Any changes to the Scheme of Work shall be communicated (in writing) to the Program Director and the approved revised version must be communicated to the students.
3. Module coordinators may set a more stringent similarity percentage (minimum 20%) for their respective modules pertaining to student's submissions. However, it must be communicated in writing to the respective Programme Director (PD) and the approved revised version must be communicated to the students.